Advanced Methods for Bayesian Optimization in Complex Scenarios Course

Presented by: Eduardo C. Garrido-Merchán.

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Quantitative Methods Department

Former PhD student of Daniel Hernandez Lobato

June, 2024.

► Introduction and Motivation.

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- ► Fundamentals of Bayesian Optimization.

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- ► Hands on Bayesian optimization with BOTorch.

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- ▶ Parallel Constrained Multi-objective Bayesian optimization.
- Advanced scenarios: Mixed, multi-fidelity, high-dim, topologies.

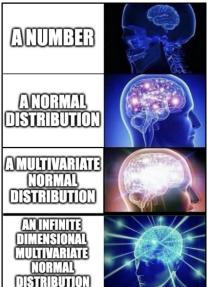
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- References.

First Session: Bayesian optimization fundamentals

Introduction.

GPs are great... so now... how can they be used for optimization?









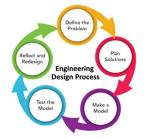












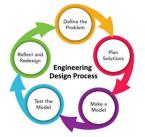
Companies face complex scenarios dealing with lots of scenarios!











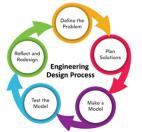
Many choices at each step.











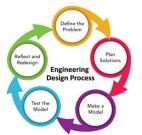
- Many choices at each step.
- Complicated and high dimensional.











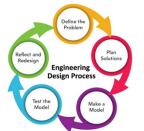
- ► Many choices at each step.
- Complicated and high dimensional.
- Difficult for individuals to reason about.











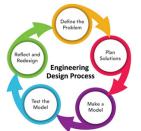
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- ► Many choices at each step.
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- Difficult for individuals to reason about.
- Prone to human bias.
- It may be possible to test various models in parallel.

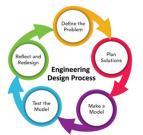
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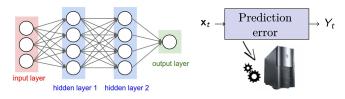


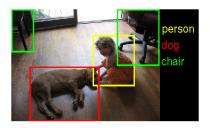


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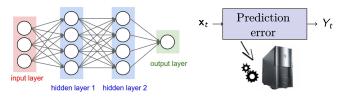
Optimization is a challenging task in real-life choices!

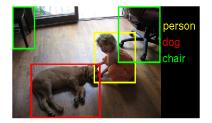
Example: Deep Neural Network for object recognition.





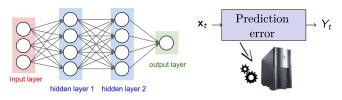
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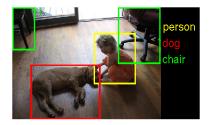




Parameters to tune: Number of neurons, number of layers, learning-rate, level of regularization, momentum, etc.

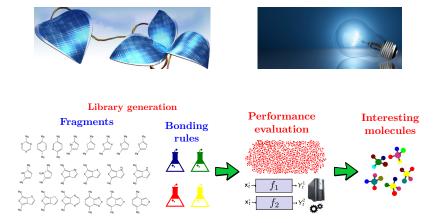
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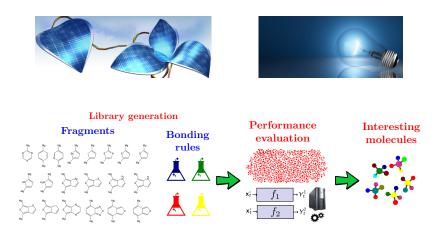


Parameters to tune: Number of neurons, number of layers, learning-rate, level of regularization, momentum, etc. If multiple processors were available, we could test various configurations in parallel, in order to gain more information.

Example: new **plastic solar cells** for transforming light into electricity.



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Explore **millions of candidate molecule structures** to identify the compounds with the best properties.

Example: control system for a robot that is able to grasp objects.







Example: **control system** for a robot that is able to grasp objects.





Parameters to tune: initial pose for the robot's hand and finger joint trajectories.

Bayesian optimization, the secret sauce of AlphaGo (and Alphazero)

Bayesian Optimization in AlphaGo

Yutian Chen, Aja Huang, Ziyu Wang, Ioannis Antonoglou, Julian Schrittwieser, David Silver & Nando de Freitas

> DeepMind, London, UK yutianc@google.com

Abstract

During the development of AlphaGo, its many hyper-parameters were tuned with gapesian optimization multiple times. This amountain tuning process residued in substantial improvements in playing strength. For example, prior to the much with a Cesdol, we tuned the latest AlphaGo agert and this improved its win-tate from 50° in 66.5° in self-play games. This tuned version was deployed in the familian match. Of conses, since we tuned AlphaGo muny times disting in development of the consession of th



Very expensive evaluations.



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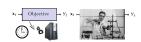
► The objective is a black-box.



Very expensive evaluations.

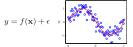


The evaluation can be noisy.









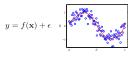
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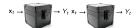


► The objective is a black-box.



► The evaluation can be noisy.





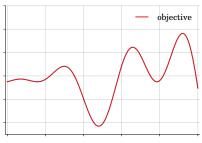
Evaluations may be done in parallel.

Bayesian optimization methods can be used to solve these problems!

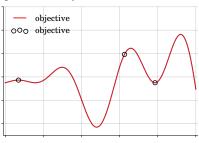
Activity

Think about a real problem that can be solved with Bayesian optimization. 15 mins individual. 10 mins in groups. 3 presentations with slides.

- Which is the function to optimize?
- Does it satisfy the BO assumptions?
- Which are the independent variables that are taken into account?
- Which are the lower and upper bounds in the optimization?
- Is f(X) a sample of a Gaussian process?
- What is the prior mean of the Gaussian process?
- ▶ Which kernel would you use?



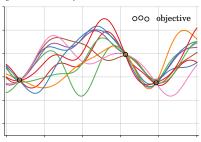
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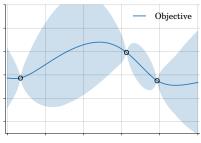
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- 2. Fit a model to the data: $p(y|x, \mathcal{D}_n).$



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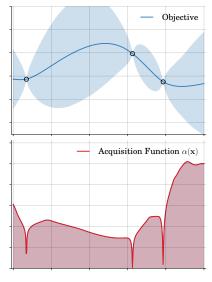
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$$\alpha(\mathsf{x}) = \mathsf{E}_{p(y|\mathsf{x},\mathcal{D}_n)}[U(y|\mathsf{x},\mathcal{D}_n)].$$



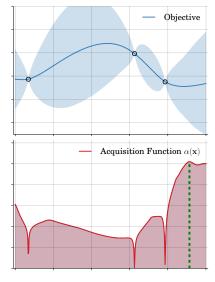
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3. Select data collection strategy:

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4. Optimize acquisition function $\alpha(x)$.

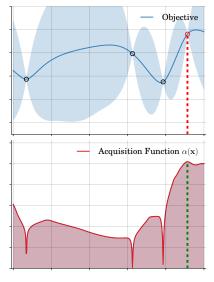


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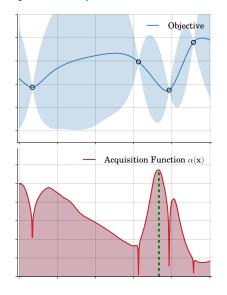


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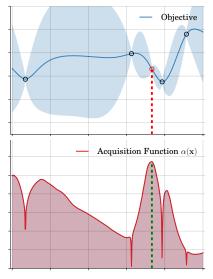


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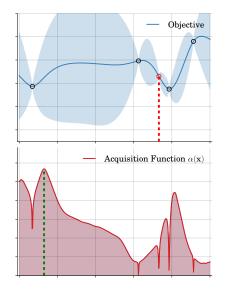


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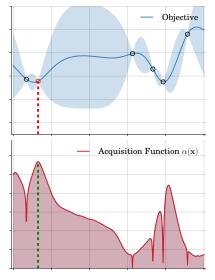


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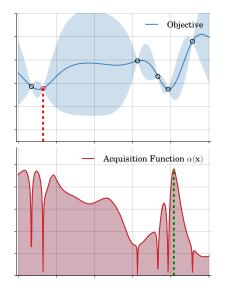


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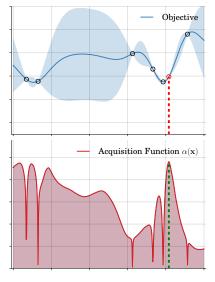


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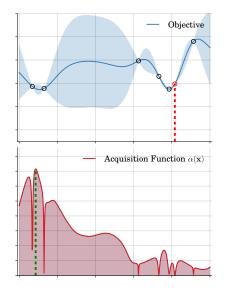


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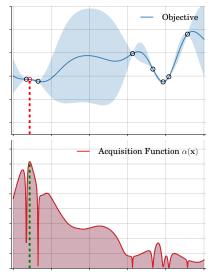


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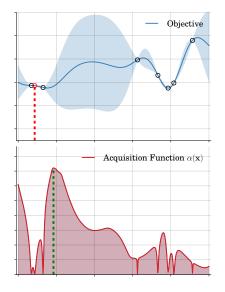


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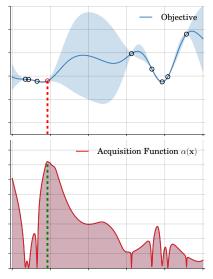


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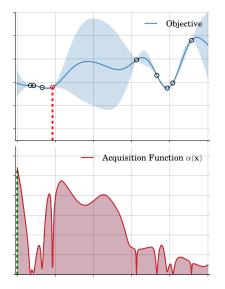


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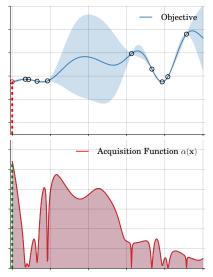


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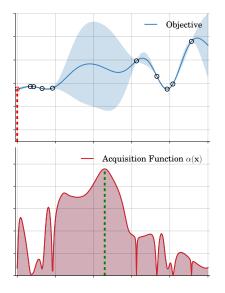


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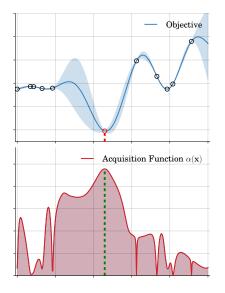


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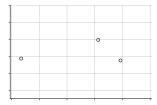


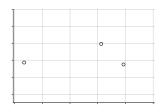
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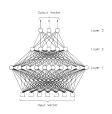
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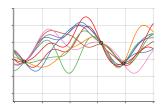


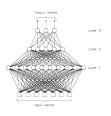




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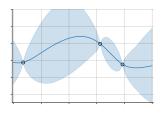
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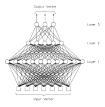




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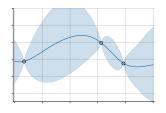
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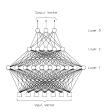




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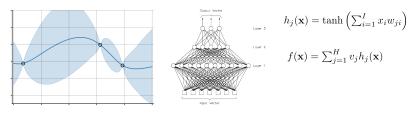
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Posterior Dist.

$$p(\mathbf{W}|\text{Data}) = p(\mathbf{W})p(\text{Data}|\mathbf{W})/p(\text{Data})$$

Predictive Dist.

$$p(y|\text{Data}, x) = \int p(y|\mathbf{W}, x)p(\mathbf{W}|\text{Data})d\mathbf{W}$$



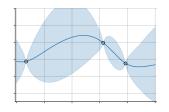
Posterior Dist.

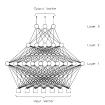
$$p(\mathbf{W}|\mathrm{Data}) = p(\mathbf{W})p(\mathrm{Data}|\mathbf{W})/p(\mathrm{Data})$$

Predictive Dist.

$$p(y|\text{Data}, x) = \int p(y|\mathbf{W}, x)p(\mathbf{W}|\text{Data})d\mathbf{W}$$

Challenges: The model should be non-parametric (the world is complicated) and computing p(Data) is intractable!





$$h_j(\mathbf{x}) = \tanh\left(\sum_{i=1}^I x_i w_{ji}\right)$$

$$f(\mathbf{x}) = \sum_{j=1}^{H} v_j h_j(\mathbf{x})$$

Posterior Dist.

$$p(\mathbf{W}|\text{Data}) = p(\mathbf{W})p(\text{Data}|\mathbf{W})/p(\text{Data})$$

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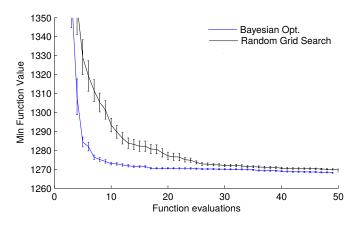
Challenges: The model should be non-parametric (the world is complicated) and computing p(Data) is intractable!

Solved by setting
$$p(W) = \prod_{ij} \mathcal{N}(w_{ji}|0, \sigma^2 H^{-1})$$
 and letting $H \to \infty!$



12/69

Bayesian Optimization vs. Uniform Exploration



Tuning LDA on a collection of Wikepida articles (Snoek et al., 2012).

Where to evaluate **next**?

Where to evaluate **next**?

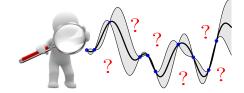


Where to evaluate **next**?



Exploration: seek places with high variance.

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- **Exploration:** seek places with high variance.
- **Exploitation:** seek places with low mean.

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$$\alpha(\mathsf{x}) = \mathbb{E}_{p(\mathsf{y}^{\star}|\mathcal{D}_{\mathsf{N}},\mathsf{x})} \left[U(\mathsf{y}^{\star}|\mathsf{x},\mathcal{D}_{\mathsf{N}}) \right]$$



Let
$$\nu = \min\{y_1, \dots, y_N\}$$
 and $\gamma(x) = \frac{\nu - \mu(x)}{\sigma(x)}$.

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▶ Lower Confidence Bound:

$$\alpha(\mathsf{x}) = -\left(\mu(\mathsf{x}) - \kappa\sigma(\mathsf{x})\right)$$



Some Acquisition Functions

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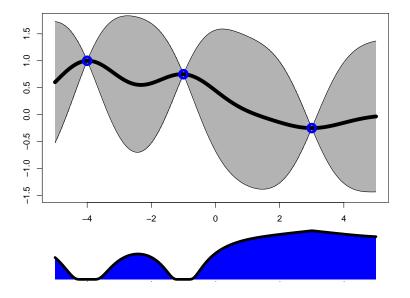
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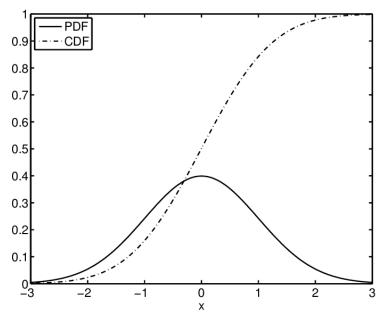
Entropy Search:

$$U(y^{\star}|\mathcal{D}_{N},x) = \mathsf{H}[p(\mathsf{x}_{\mathsf{min}}|\mathcal{D}_{N})] - \mathsf{H}[p(\mathsf{x}_{\mathsf{min}}|\mathcal{D}_{N} \cup \{\mathsf{x},y^{\star}\})]$$

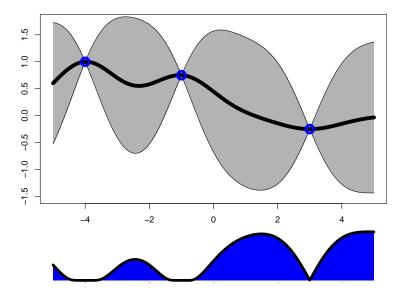
Some Acquisition Functions: Prob. Improvement



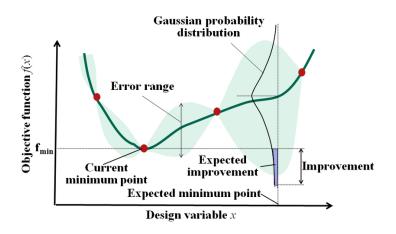
Prob. Improvement: CDF



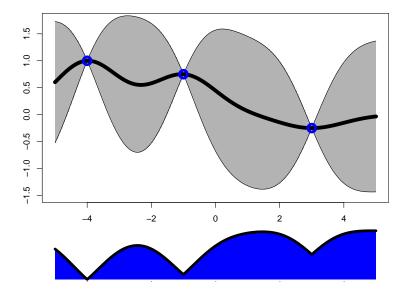
Some Acquisition Functions: Exp. Improvement



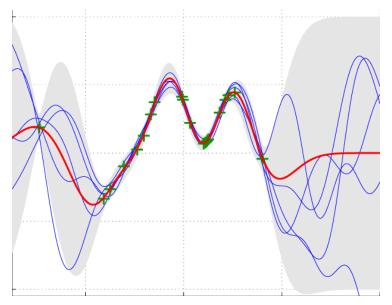
Expected Improvement: intuition



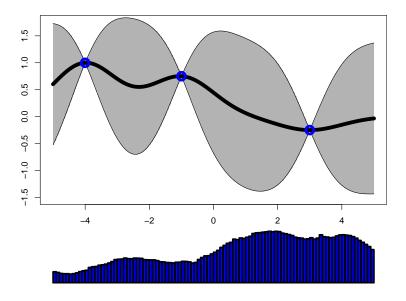
Some Acquisition Functions: Lower Conf. Bound

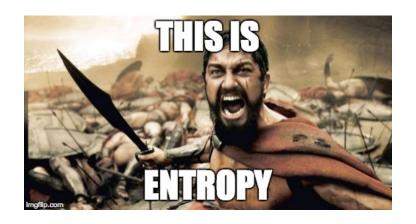


kappa=0. Use only GP samples and optimize to suggest!



Some Acquisition Functions: Entropy Search

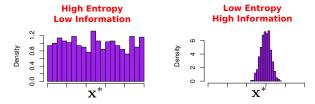




The minimizer, x^* , can be modelled as a **random variable! Information** is measured by the **entropy** of $p(x^*|\mathcal{D})$.

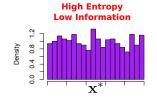
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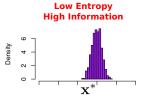
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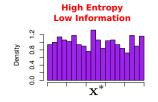


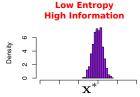


$$\alpha(\mathbf{x}) = \mathsf{H}\big[\mathbf{x}^*|\mathcal{D}_t\big] - \mathbb{E}_{\mathbf{y}}\Big[\mathsf{H}\big[\mathbf{x}^*|\mathcal{D}_t \cup \{\mathbf{x}, \mathbf{y}\}\big]\Big|\mathcal{D}_t, \mathbf{x}\Big] \quad (1)$$

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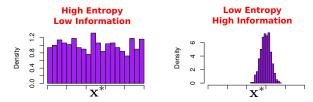




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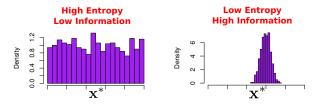


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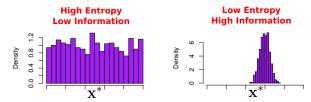


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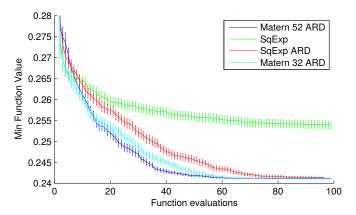


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Structured SVM for protein motif finding (Snoek et al., 2012).

▶ Hyper-parameter selection: with a small number of observations maximizing $p(y|\theta)$ can give too confident uncertainty estimates.

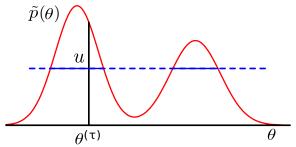
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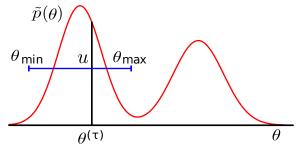
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(Neal, 2003)

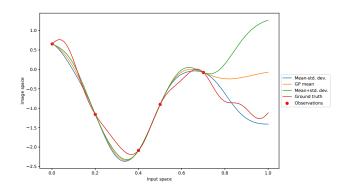
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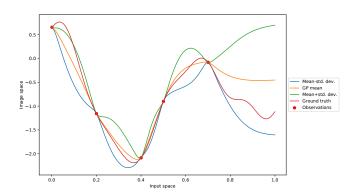


(Neal, 2003)

GP fitting an unknown function using Maximum Likelihood



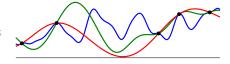
GP fitting an unknown function sampling hyperparameters



$$\hat{\alpha}(\mathbf{x}) = \int \alpha(\mathbf{x}; \theta) p(\theta|\mathbf{y}) d\theta \approx \frac{1}{K} \sum_{k=1}^{K} \alpha(\mathbf{x}; \theta^{(k)}) \quad \theta^{(k)} \sim p(\theta|\mathbf{y}),$$

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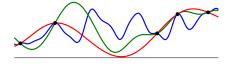
Posterior samples with three different length-scales



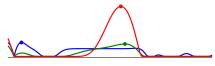


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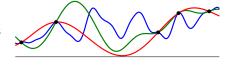


Length-scale specific expected improvement

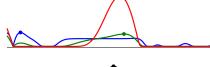


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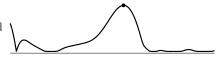
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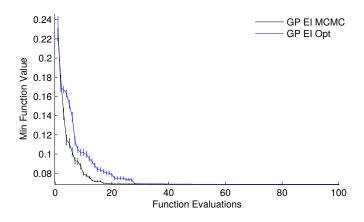
Length-scale specific expected improvement



Integrated expected improvement



MCMC estimation vs. Maximization



Logistic regression on the MNIST (Snoek et al., 2012).

Different inputs may have different computational costs, e.g., training a neural network of increasing hidden layers and units.

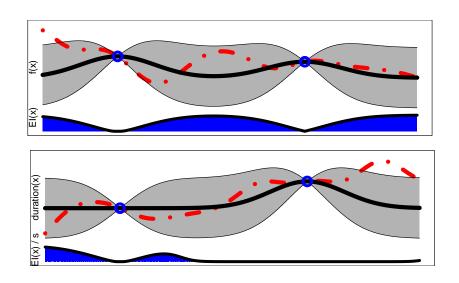
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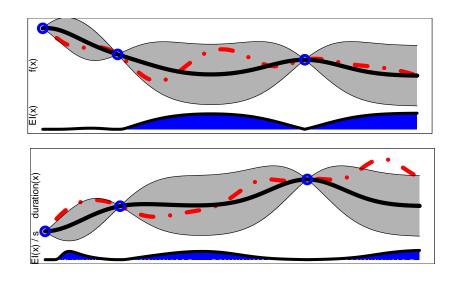
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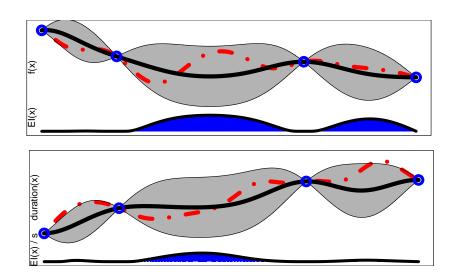
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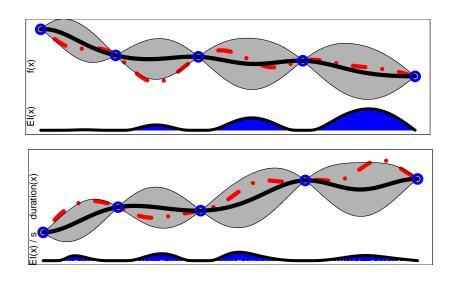
Expected Improvement per-second:

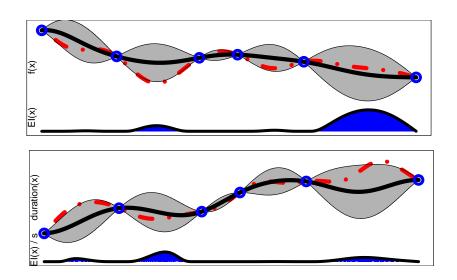
$$\alpha(x) = \frac{\sigma(x) (\gamma(x) \Phi(\gamma(x)) + \phi(\gamma(x)))}{\exp \{\mu_{\text{log-time}}(x)\}}$$

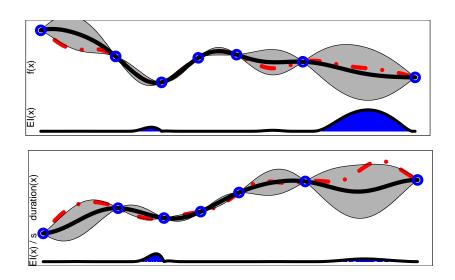


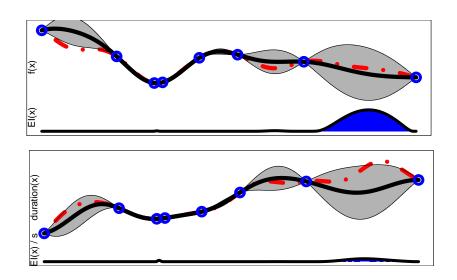


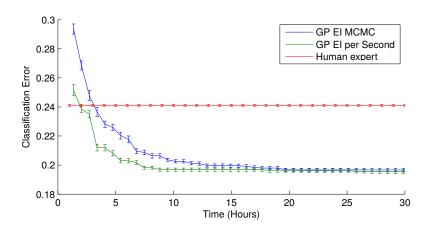












Deep neural network on the CIFAR dataset (Snoek et al., 2012)

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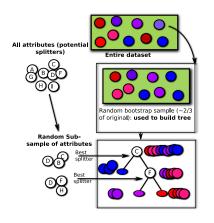
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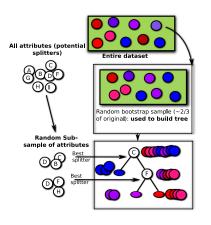
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- 5. **Bayesian neural networks**: Able to model complex patterns and scalable.
- Deep Gaussian Process: Increased expressivity, advantages of GPs.

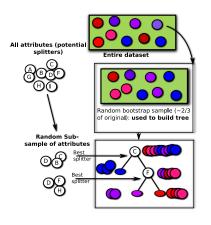
Ensemble method where the predictors are random regression trees trained on random subsamples of the data.



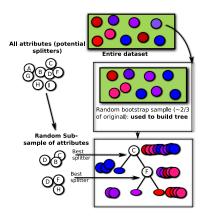
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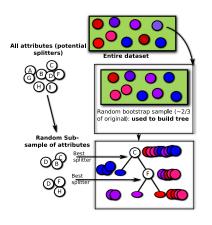


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- At each node the best splitter is chosen randomly.
- Leaf nodes predict the average value of the points reaching that node.
- ► This guarantees that each tree is slightly different.

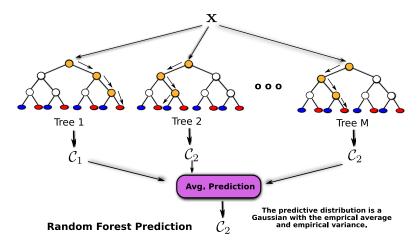
Ensemble method where the predictors are random regression trees trained on random subsamples of the data.



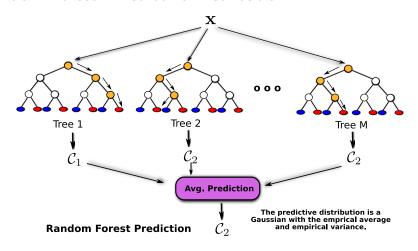
- Trees are grown on different bootstrap samples of the data.
- At each node the best splitter is chosen randomly.
- ► Leaf nodes predict the average value of the points reaching that node.
- This guarantees that each tree is slightly different.

Very cheap to compute and massively paralelizable!

Random Forest: Predictive Distribution



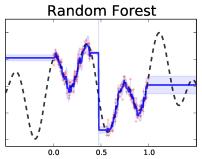
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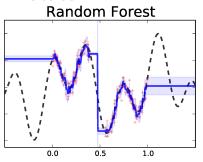


$$p(f^{\star}|\mathcal{D}_n) = \mathcal{N}(f^{\star}|\overline{\mu}, \overline{\nu}^2)$$

(Hutter et al., 2011)

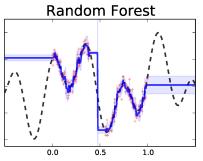




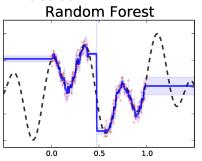


(Shahriari et al., 2016)

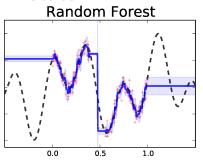
► Allows for a lot of evaluations (good when the objective is cheap).



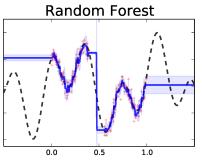
- ► Allows for a lot of evaluations (good when the objective is cheap).
- ▶ Too confident intervals in far away from the data regions.



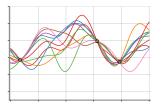
- ► Allows for a lot of evaluations (good when the objective is cheap).
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- ► Conflictive predictions can cause the variance to be too high.

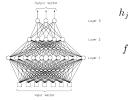


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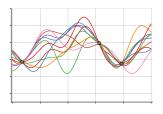
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- No parameters to tune.

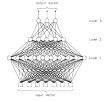




$$h_j(\mathbf{x}) = \tanh\left(\sum_{i=1}^{I} x_i w_{ji}\right)$$
$$f(\mathbf{x}) = \sum_{j=1}^{H} v_j h_j(\mathbf{x})$$

Neural networks scale well to the training data (linear cost).

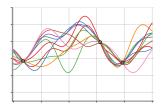


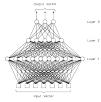


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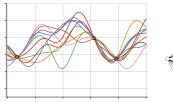


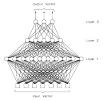


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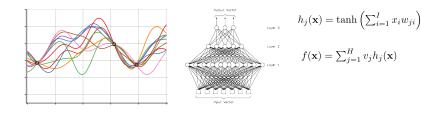




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The posterior distribution of the networks weights W is intractable!



Several techniques considered to approximate the predictive distribution:

Markov Chain Monte Carlo methods.

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Trade-off between accuracy of the predictive distribution and scalability! Still a lot of research going on!

Activity: Bayesian optimization of a ML algorithm

Use a generative AI to generate a BO code of a ML hyperparameter problem.

- Try to execute the code in your machine and fix it.
- Try to interpret everything.
- Tune it and improve the quality of the error estimator.
- Try to improve it with additional acquisition functions.
- ▶ Try to obtain the best score in the titanic problem with BO-ML!

Many of the methods described are implemented into **BOTorch** using Python.

https://botorch.org/



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Other tools: SMAC3 (Python-RFs), GPyOpt (Python3), Spearmint (Python2.7-sampling), mlrMBO (R).

Time to practice!

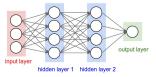
- 1. Bayesian optimization of a benchmark optimization function.
- 2. Bayesian optimization of the hyper-parameters of a machine learning model.
- 3. Bayesian optimization of the hyper-paramaters of a deep reinforcement learning algorithm.



Second Session: Advanced Bayesian optimization.

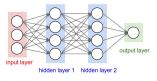
(Parallel) Multi-objective Bayesian optimization with constraints.

Optimal design of **hardware accelerator** for neural network predictions.





Optimal design of **hardware accelerator** for neural network predictions.

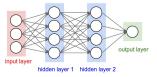




Goals:

- Minimize prediction error.
- Minimize prediction time.

Optimal design of **hardware accelerator** for neural network predictions.





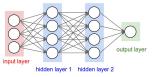
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- Chip area below a value.
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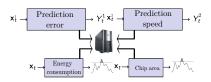


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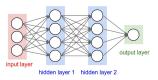
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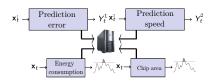


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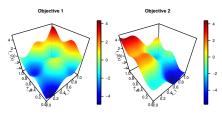
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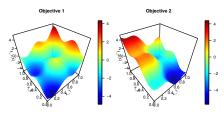


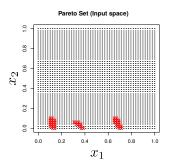
Challenges:

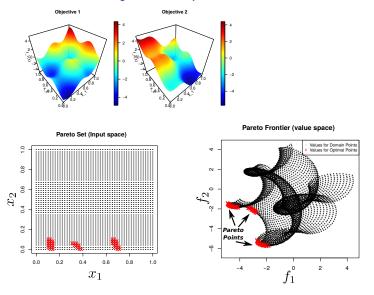
- Complicated constraints.
- Conflictive objectives.

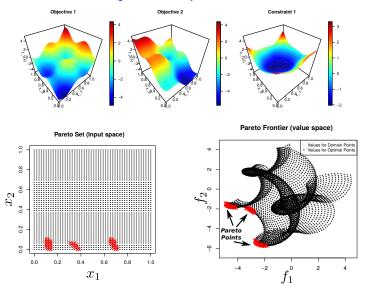


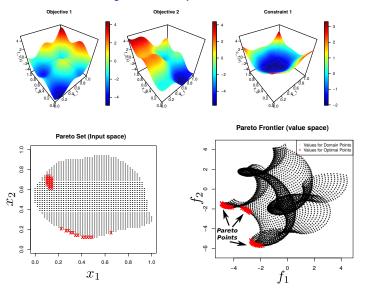


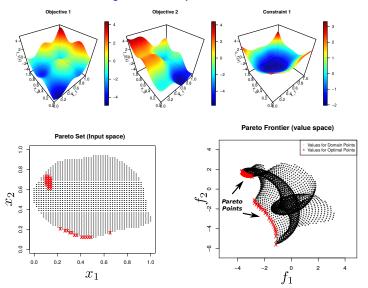












Additional challenges when dealing with several black-boxes.

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➤ Simple approach: evaluate **all** the objectives and constraints at the **same input location**. Expected to be sub-optimal.

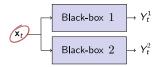
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Coupled evaluations

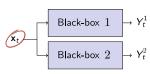




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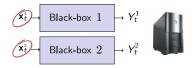
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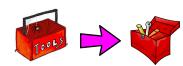
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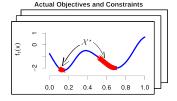


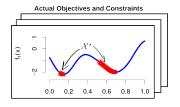
Decoupled evaluations

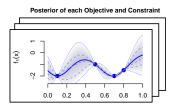


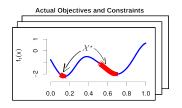


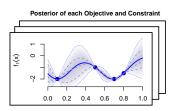
The Pareto set \mathcal{X}^* in the feasible space is a **random variable**!

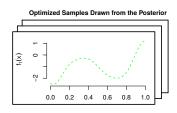


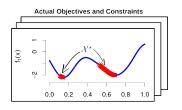


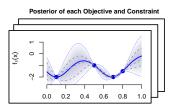


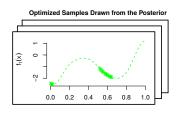


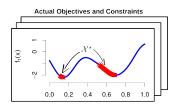


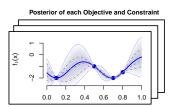


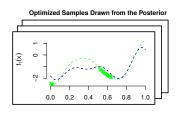


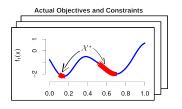


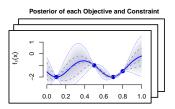


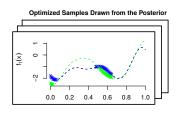




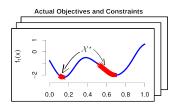


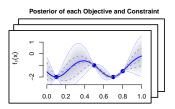


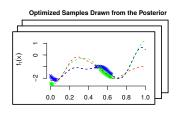




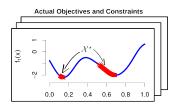
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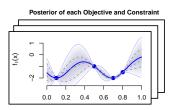


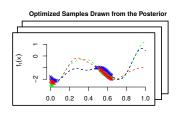




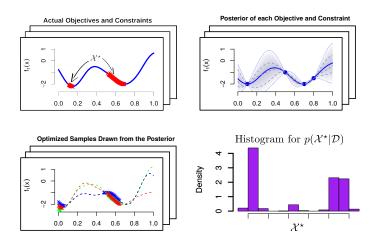
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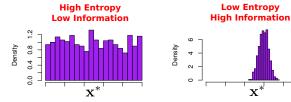
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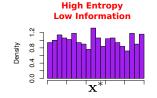
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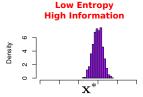
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The acquisition function is

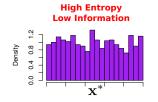
$$\alpha(\mathbf{x}) = \mathsf{H}\big[\mathbf{x}^*|\mathcal{D}_t\big] - \mathbb{E}_{\mathbf{y}}\Big[\mathsf{H}\big[\mathbf{x}^*|\mathcal{D}_t \cup \{\mathbf{x},\mathbf{y}\}\big]\Big|\mathcal{D}_t,\mathbf{x}\Big] \quad (1)$$

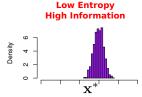


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Information is measured by the **entropy** of $p(\mathcal{X}^*|\mathcal{D}_N)$.

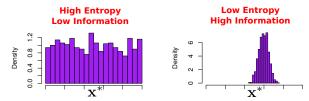




$$\alpha(\mathbf{x}) = \mathbf{H}[\mathbf{x}^* | \mathcal{D}_t] - \mathbb{E}_{\mathbf{y}} \Big[\mathbf{H}[\mathbf{x}^* | \mathcal{D}_t \cup \{\mathbf{x}, \mathbf{y}\}] \, \Big| \, \mathcal{D}_t, \mathbf{x} \Big]$$
How much we know about \mathbf{X}^* now.

The Pareto set \mathcal{X}^* in the feasible space is a **random variable**!

Information is measured by the **entropy** of $p(\mathcal{X}^*|\mathcal{D}_N)$.



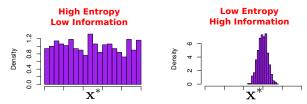
$$\alpha\left(\mathbf{x}\right) = \mathbf{H}\left[\mathbf{x}^*|\mathcal{D}_t\right] - \mathbb{E}_{\mathbf{y}}\left[\mathbf{H}\left[\mathbf{x}^*|\mathcal{D}_t \cup \left\{\mathbf{x},\mathbf{y}\right\}\right]\middle|\mathcal{D}_t,\mathbf{x}\right]$$

$$\text{How much we know about } \mathbf{x}^* \text{ now.}$$

$$\text{How much we will know about } \mathbf{x}^* \text{ after collecting } \mathbf{y} \text{ at } \mathbf{x}.$$

The Pareto set \mathcal{X}^* in the feasible space is a **random variable**!

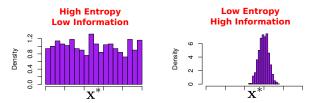
Information is measured by the **entropy** of $p(\mathcal{X}^*|\mathcal{D}_N)$.

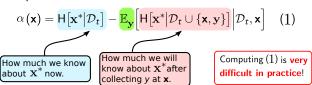


$$\alpha\left(\mathbf{x}\right) = \mathbf{H}\left[\mathbf{x}^*|\mathcal{D}_t\right] - \mathbb{E}_{\mathbf{y}}\left[\mathbf{H}\left[\mathbf{x}^*|\mathcal{D}_t \cup \left\{\mathbf{x},\mathbf{y}\right\}\right] \middle| \mathcal{D}_t,\mathbf{x}\right]$$
How much we know about \mathbf{x}^* after collecting \mathbf{y} at \mathbf{x} .

The Pareto set \mathcal{X}^* in the feasible space is a **random variable**!

Information is measured by the **entropy** of $p(\mathcal{X}^*|\mathcal{D}_N)$.





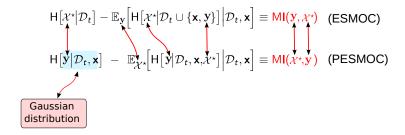
$$\mathsf{H}\big[\mathcal{X}^{\star}\big|\mathcal{D}_{t}\big] - \mathbb{E}_{\mathbf{y}}\Big[\mathsf{H}\big[\mathcal{X}^{\star}\big|\mathcal{D}_{t} \cup \{\mathbf{x},\mathbf{y}\}\big]\Big|\mathcal{D}_{t},\mathbf{x}\Big] \equiv \textcolor{red}{\mathsf{MI}(\mathbf{y},\mathcal{X}^{\star})} \quad \text{(ESMOC)}$$

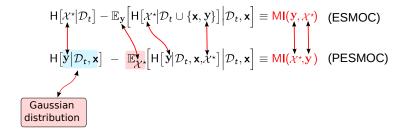
$$\begin{split} & H\big[\mathcal{X}^{\star}\big|\mathcal{D}_{t}\big] - \mathbb{E}_{\mathbf{y}}\Big[H\big[\mathcal{X}^{\star}\big|\mathcal{D}_{t} \cup \{\mathbf{x},\mathbf{y}\}\big]\Big|\mathcal{D}_{t},\mathbf{x}\Big] \equiv \mathsf{MI}(\mathbf{y},\mathcal{X}^{\star}) \quad \text{(ESMOC)} \\ & H\big[\mathbf{y}\big|\mathcal{D}_{t},\mathbf{x}\big] \ - \ \mathbb{E}_{\mathcal{X}^{\star}}\Big[H\big[\mathbf{y}\big|\mathcal{D}_{t},\mathbf{x},\mathcal{X}^{\star}\big]\Big|\mathcal{D}_{t},\mathbf{x}\Big] \equiv \mathsf{MI}(\mathcal{X}^{\star},\mathbf{y}) \quad \text{(PESMOC)} \end{split}$$

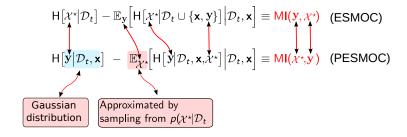
$$\begin{split} & \mathsf{H}\big[\mathcal{X}^{\star}|\mathcal{D}_{t}\big] - \mathbb{E}_{\mathbf{y}}\Big[\mathsf{H}\big[\mathcal{X}^{\star}|\mathcal{D}_{t} \cup \{\mathbf{x},\mathbf{y}\}\big] \Big| \mathcal{D}_{t},\mathbf{x}\Big] \equiv \mathsf{MI}(\mathbf{y},\mathcal{X}^{\star}) \quad \text{(ESMOC)} \\ & \mathsf{H}\big[\mathbf{y}|\mathcal{D}_{t},\mathbf{x}\big] - \mathbb{E}_{\mathcal{X}^{\star}}\Big[\mathsf{H}\big[\mathbf{y}|\mathcal{D}_{t},\mathbf{x},\mathcal{X}^{\star}\big] \Big| \mathcal{D}_{t},\mathbf{x}\Big] \equiv \mathsf{MI}(\mathcal{X}^{\star},\mathbf{y}) \quad \text{(PESMOC)} \end{split}$$

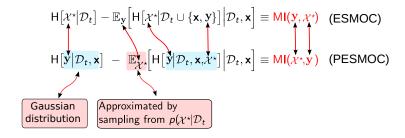
$$\begin{split} & \mathbf{H} \big[\boldsymbol{\mathcal{X}}^{\star} \big| \mathcal{D}_{t} \big] - \mathbb{E}_{\mathbf{y}} \Big[\mathbf{H} \big[\boldsymbol{\mathcal{X}}^{\star} \big| \mathcal{D}_{t} \cup \{\mathbf{x}, \mathbf{y}\} \big] \, \Big| \mathcal{D}_{t}, \mathbf{x} \Big] \equiv \mathbf{MI} \big(\mathbf{y}, \boldsymbol{\mathcal{X}}^{\star} \big) & \text{(ESMOC)} \\ & \mathbf{H} \big[\mathbf{y} \big| \mathcal{D}_{t}, \mathbf{x} \big] \, - \, \mathbb{E}_{\boldsymbol{\mathcal{X}}^{\star}} \Big[\mathbf{H} \big[\mathbf{y} \big| \mathcal{D}_{t}, \mathbf{x}, \boldsymbol{\mathcal{X}}^{\star} \big] \, \Big| \mathcal{D}_{t}, \mathbf{x} \Big] \equiv \mathbf{MI} \big(\boldsymbol{\mathcal{X}}^{\star}, \mathbf{y} \big) & \text{(PESMOC)} \end{split}$$

$$\begin{split} & \mathbf{H} \big[\boldsymbol{\mathcal{X}}^{\star} | \mathcal{D}_{t} \big] - \mathbb{E}_{\mathbf{y}} \Big[\mathbf{H} \big[\boldsymbol{\mathcal{X}}^{\star} | \mathcal{D}_{t} \cup \{\mathbf{x}, \mathbf{y}\} \big] \Big| \mathcal{D}_{t}, \mathbf{x} \Big] \equiv \mathbf{MI} (\mathbf{y}, \boldsymbol{\mathcal{X}}^{\star}) & \text{(ESMOC)} \\ & \mathbf{H} \big[\mathbf{y} | \mathcal{D}_{t}, \mathbf{x} \big] - \mathbb{E}_{\boldsymbol{\mathcal{X}}^{\star}} \Big[\mathbf{H} \big[\mathbf{y} | \mathcal{D}_{t}, \mathbf{x}, \dot{\boldsymbol{\mathcal{X}}^{\star}} \big] \Big| \mathcal{D}_{t}, \mathbf{x} \Big] \equiv \mathbf{MI} (\boldsymbol{\mathcal{X}}^{\star}, \mathbf{y}) & \text{(PESMOC)} \end{split}$$









We **swap** y **and** \mathcal{X}^* to obtain a reformulation of the acquisition function.

$$\begin{aligned} &\mathsf{H}\big[\mathcal{X}^{\star}|\mathcal{D}_{t}\big] - \mathbb{E}_{\mathbf{y}}\Big[\mathsf{H}\big[\mathcal{X}^{\star}|\mathcal{D}_{t} \cup \{\mathbf{x},\mathbf{y}\}\big] \Big| \mathcal{D}_{t},\mathbf{x}\Big] \equiv \mathsf{MI}(\mathbf{y},\mathcal{X}^{\star}) \quad \text{(ESMOC)} \\ &\mathsf{H}\big[\mathbf{y}|\mathcal{D}_{t},\mathbf{x}\big] - \mathbb{E}_{\mathcal{X}^{\star}}\Big[\mathsf{H}\big[\mathbf{y}|\mathcal{D}_{t},\mathbf{x},\mathcal{X}^{\star}\big] \Big| \mathcal{D}_{t},\mathbf{x}\Big] \equiv \mathsf{MI}(\mathcal{X}^{\star},\mathbf{y}) \quad \text{(PESMOC)} \\ &\mathsf{Gaussian} \quad \mathsf{Approximated by} \quad \mathsf{Sampling from } p(\mathcal{X}^{\star}|\mathcal{D}_{t}) \\ &\mathsf{sampling from } p(\mathcal{X}^{\star}|\mathcal{D}_{t}) \\ &\mathsf{X}^{\star} \quad \mathsf{dominates any other point in } \quad \mathcal{X} \end{aligned}.$$

We **swap** y **and** \mathcal{X}^* to obtain a reformulation of the acquisition function.

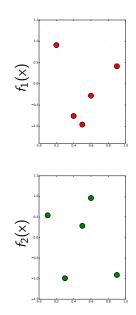
$$\begin{aligned} & \text{H}\big[\mathcal{X}^{\star}|\mathcal{D}_{t}\big] - \mathbb{E}_{\mathbf{y}}\Big[\text{H}\big[\mathcal{X}^{\star}|\mathcal{D}_{t} \cup \{\mathbf{x},\mathbf{y}\}\big]\Big|\mathcal{D}_{t},\mathbf{x}\Big] \equiv \text{MI}(\mathbf{y},\mathcal{X}^{\star}) \quad \text{(ESMOC)} \\ & \text{H}\big[\mathbf{y}|\mathcal{D}_{t},\mathbf{x}\big] - \mathbb{E}_{\mathbf{x}^{\star}}\Big[\text{H}\big[\mathbf{y}|\mathcal{D}_{t},\mathbf{x},\mathcal{X}^{\star}\big]\Big|\mathcal{D}_{t},\mathbf{x}\Big] \equiv \text{MI}(\mathcal{X}^{\star},\mathbf{y}) \quad \text{(PESMOC)} \\ & \text{Gaussian} \quad \text{Approximated by sampling from } p(\mathcal{X}^{\star}|\mathcal{D}_{t}) \quad \text{with } \underbrace{\text{expectation propagation.}}_{\text{with expectation propagation.}} \\ & \alpha(\mathbf{x}) \approx \sum_{c=1}^{C} \log v_{c}^{PD}(\mathbf{x}) - \frac{1}{M} \sum_{m=1}^{M} \left(\sum_{c=1}^{C} \log v_{c}^{CPD}(\mathbf{x}|\mathcal{X}_{(m)}^{\star})\right) + \\ & \sum_{k=1}^{K} \log v_{k}^{PD}(\mathbf{x}) - \frac{1}{M} \sum_{m=1}^{M} \left(\sum_{k=1}^{K} \log v_{k}^{CPD}(\mathbf{x}|\mathcal{X}_{(m)}^{\star})\right) \end{aligned}$$

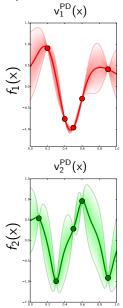
We **swap** y **and** \mathcal{X}^* to obtain a reformulation of the acquisition function.

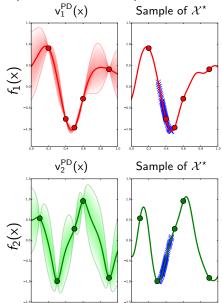
$$\begin{aligned} & \mathsf{H}\big[\mathcal{X}^{\star}|\mathcal{D}_{t}\big] - \mathbb{E}_{\mathbf{y}}\Big[\mathsf{H}\big[\mathcal{X}^{\star}|\mathcal{D}_{t} \cup \{\mathbf{x},\mathbf{y}\}\big]\Big|\mathcal{D}_{t},\mathbf{x}\Big] \equiv \mathsf{MI}(\mathbf{y},\mathcal{X}^{\star}) \quad \text{(ESMOC)} \\ & \mathsf{H}\big[\dot{\mathbf{y}}|\mathcal{D}_{t},\mathbf{x}\big] - \mathbb{E}_{\mathcal{X}^{\star}}\Big[\mathsf{H}\big[\dot{\mathbf{y}}|\mathcal{D}_{t},\mathbf{x},\mathcal{X}^{\star}\big]\Big|\mathcal{D}_{t},\mathbf{x}\Big] \equiv \mathsf{MI}(\mathcal{X}^{\star},\mathbf{y}) \quad \text{(PESMOC)} \\ & \mathsf{Gaussian} \quad \mathsf{Approximated by} \quad \mathsf{Sampling from } p(\mathcal{X}^{\star}|\mathcal{D}_{t}) \\ & \mathsf{sampling from } p(\mathcal{X}^{\star}|\mathcal{D}_{t}) \\ & \mathsf{x}^{\star} \quad \mathsf{dominates any other point in } \mathcal{X} \end{aligned}.$$

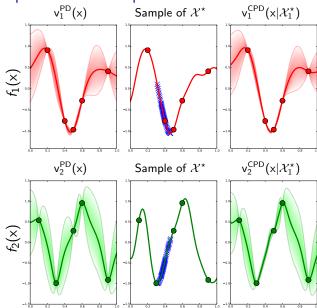
We **swap** y **and** \mathcal{X}^* to obtain a reformulation of the acquisition function.

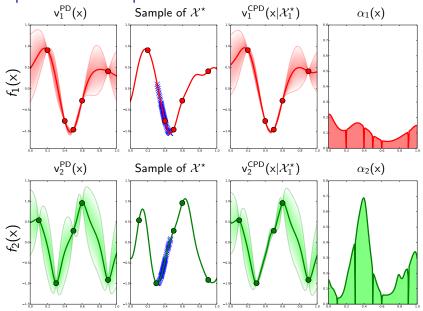
$$\begin{aligned} & \mathsf{H}\big[\mathcal{X}^{\star}\big|\mathcal{D}_{t}\big] - \mathbb{E}_{\mathbf{y}}\Big[\mathsf{H}\big[\mathcal{X}^{\star}\big|\mathcal{D}_{t} \cup \{\mathbf{x},\mathbf{y}\}\big]\Big|\mathcal{D}_{t},\mathbf{x}\Big] \equiv \mathsf{MI}(\mathbf{y},\mathcal{X}^{\star}) \quad \text{(ESMOC)} \\ & \mathsf{H}\big[\dot{\mathbf{y}}\big|\mathcal{D}_{t},\mathbf{x}\big] - \mathbb{E}_{\mathcal{X}^{\star}}\Big[\mathsf{H}\big[\dot{\mathbf{y}}\big|\mathcal{D}_{t},\mathbf{x},\mathcal{X}^{\star}\big]\Big|\mathcal{D}_{t},\mathbf{x}\Big] \equiv \mathsf{MI}(\mathcal{X}^{\star},\mathbf{y}) \quad \text{(PESMOC)} \\ & \mathsf{Gaussian} \quad \text{Approximated by sampling from } p(\mathcal{X}^{\star}|\mathcal{D}_{t}) \\ & \mathsf{sampling from } p(\mathcal{X}^{\star}|\mathcal{D}_{t}) \\ & \mathsf{with } \underbrace{\mathsf{expectation}}_{\mathsf{value}} \quad \mathsf{One acquisition}_{\mathsf{per black-box}} \\ & \mathsf{value}_{\mathsf{value}} \quad \mathsf{value}_{\mathsf{value}} \quad \mathsf{value}_{\mathsf{value}} \quad \mathsf{value}_{\mathsf{value}} \quad \mathsf{value}_{\mathsf{value}} \\ & \mathsf{value}_{\mathsf{value}} \quad \mathsf{value}_{\mathsf{value}} \quad \mathsf{value}_{\mathsf{value}} \quad \mathsf{value}_{\mathsf{value}} \\ & \mathsf{value}_{\mathsf{value}} \quad \mathsf{value}_{\mathsf{value}} \quad \mathsf{value}_{\mathsf{value}} \quad \mathsf{value}_{\mathsf{value}} \quad \mathsf{value}_{\mathsf{value}} \\ & \mathsf{value}_{\mathsf{value}} \quad \mathsf{value}_{\mathsf{value}} \quad \mathsf{value}_{\mathsf{value}} \quad \mathsf{value}_{\mathsf{value}} \\ & \mathsf{value}_{\mathsf{value}} \quad \mathsf{value}_{\mathsf{value}} \quad \mathsf{value}_{\mathsf{value}} \quad \mathsf{value}_{\mathsf{value}} \quad \mathsf{value}_{\mathsf{value}} \\ & \mathsf{value}_{\mathsf{value}} \quad \mathsf{va$$

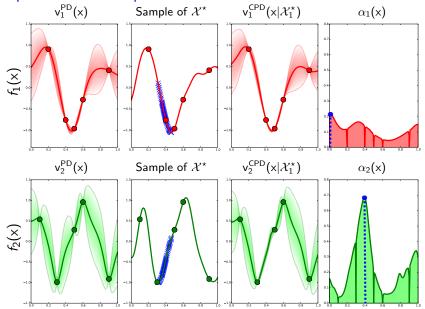




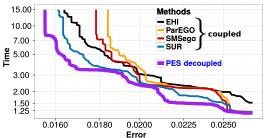




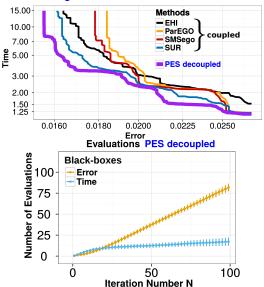




Finding a Fast and Accurate Neural Network Average Pareto Front 100 Function Evaluations

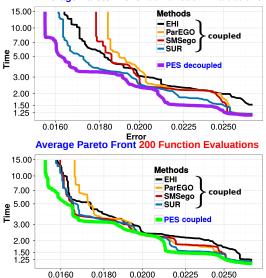


Finding a Fast and Accurate Neural Network
Average Pareto Front 100 Function Evaluations



(Hernández-Lobato et al., 2016)

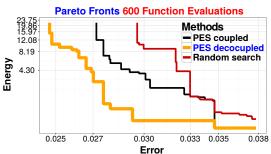
Finding a Fast and Accurate Neural Network
Average Pareto Front 100 Function Evaluations



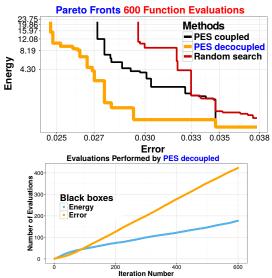
Error

(Hernández-Lobato et al., 2016)

Low energy hardware accelerator



Low energy hardware accelerator

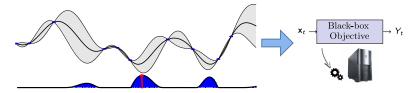


(Hernández-Lobato et al., 2016)

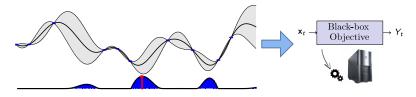
Parallel Bayesian Optimization

Traditional Bayesian optimization is sequential!

Traditional Bayesian optimization is sequential!

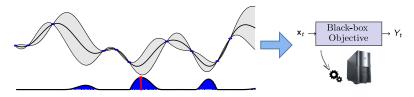


Traditional Bayesian optimization is sequential!

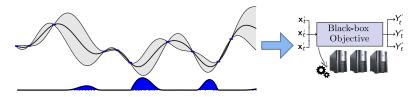


Computing clusters let us do many things at once!

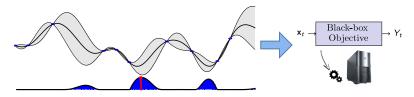
Traditional Bayesian optimization is sequential!



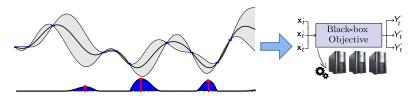
Computing clusters let us do many things at once!



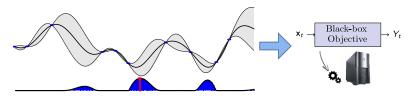
Traditional Bayesian optimization is sequential!



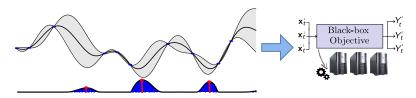
Computing clusters let us do many things at once!



Traditional Bayesian optimization is sequential!



Computing clusters let us do many things at once!



Parallel experiments should be highly informative but different!

Choose a set Q points $S_t = \{x_q\}_{q=1}^Q$ to minimize the entropy of x^* .

$$\mathsf{H}\big[\mathbf{x}^{\star}\big|\mathcal{D}_{t}\big] - \mathbb{E}_{\mathbf{y}}\Big[\mathsf{H}\big[\mathbf{x}^{\star}\big|\mathcal{D}_{t} \cup \{\mathbf{x}_{q},y_{q}\}_{q=1}^{Q}\big]\Big|\mathcal{D}_{t},\mathbf{x}\Big] \equiv \mathsf{MI}(\mathbf{\underline{y}},\mathbf{x}^{\star}) \quad \text{(Parallel ES)}$$

Choose a set Q points $S_t = \{x_q\}_{q=1}^Q$ to minimize the entropy of x^* .

$$\mathsf{H}\big[\mathbf{x}^{\star}\big|\mathcal{D}_{t}\big] - \mathbb{E}_{\mathbf{y}}\Big[\mathsf{H}\big[\mathbf{x}^{\star}\big|\mathcal{D}_{t} \cup \{\mathbf{x}_{q},y_{q}\}_{q=1}^{Q}\big]\Big|\mathcal{D}_{t},\mathbf{x}\Big] \equiv \mathsf{MI}(\mathbf{y},\mathbf{x}^{\star}) \quad \text{(Parallel ES)}$$

$$\mathsf{H}\big[\mathbf{y}\big|\mathcal{D}_t,\mathbf{x}\big] \ - \ \mathbb{E}_{\mathbf{x}^\star}\Big[\mathsf{H}\big[\mathbf{y}\big|\mathcal{D}_t,\mathbf{x},\mathbf{x}^\star\big]\Big|\mathcal{D}_t,\mathbf{x}\Big] \equiv \mathsf{MI}(\mathbf{x}^\star,\mathbf{y}) \quad \text{(Parallel PES)}$$

Choose a set Q points $S_t = \{x_q\}_{q=1}^Q$ to minimize the entropy of x^* .

$$\begin{split} &\mathsf{H}\big[\mathbf{x}^{\star}\big|\mathcal{D}_{t}\big] - \mathbb{E}_{\mathbf{y}}\Big[\mathsf{H}\big[\mathbf{x}^{\star}\big|\mathcal{D}_{t} \cup \{\mathbf{x}_{q}, y_{q}\}_{q=1}^{Q}\big] \, \Big| \mathcal{D}_{t}, \mathbf{x}\Big] \equiv \mathsf{MI}(\mathbf{y}, \mathbf{x}^{\star}) \quad \text{(Parallel ES)} \\ &\mathsf{H}\big[\dot{\mathbf{y}}\big|\mathcal{D}_{t}, \mathbf{x}\big] \, - \, \, \mathbb{E}_{\mathbf{x}^{\star}}^{\mathsf{T}}\Big[\mathsf{H}\big[\dot{\mathbf{y}}\big|\mathcal{D}_{t}, \mathbf{x}, \mathbf{x}^{\star}\big] \, \Big| \mathcal{D}_{t}, \mathbf{x}\Big] \equiv \mathsf{MI}(\mathbf{x}^{\star}, \mathbf{y}) \quad \text{(Parallel PES)} \end{split}$$

Choose a set Q points $S_t = \{x_q\}_{q=1}^Q$ to minimize the entropy of x^* .

$$\begin{split} &\mathsf{H}\big[\mathbf{x}^{\star}\big|\mathcal{D}_{t}\big] - \mathbb{E}_{\mathbf{y}}\Big[\mathsf{H}\big[\mathbf{x}^{\star}\big|\mathcal{D}_{t} \cup \{\mathbf{x}_{q}, y_{q}\}_{q=1}^{Q}\big] \, \Big| \mathcal{D}_{t}, \mathbf{x}\Big] \equiv \mathsf{MI}(\mathbf{y}, \mathbf{x}^{\star}) \quad \text{(Parallel ES)} \\ &\mathsf{H}\big[\mathbf{y}\big|\mathcal{D}_{t}, \mathbf{x}\big] - \mathbb{E}_{\mathbf{x}^{\star}}^{\mathsf{v}}\Big[\mathsf{H}\big[\mathbf{y}\big|\mathcal{D}_{t}, \mathbf{x}, \mathbf{x}^{\star}\big] \, \Big| \mathcal{D}_{t}, \mathbf{x}\Big] \equiv \mathsf{MI}(\mathbf{x}^{\star}, \mathbf{y}) \quad \text{(Parallel PES)} \end{split}$$

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$$\begin{split} \mathsf{H}\big[\mathbf{x}^{\star}\big|\mathcal{D}_{t}\big] - \mathbb{E}_{\mathbf{y}}\Big[\mathsf{H}\big[\mathbf{x}^{\star}\big|\mathcal{D}_{t} \cup \{\mathbf{x}_{q},y_{q}\}_{q=1}^{Q}\big]\Big|\mathcal{D}_{t},\mathbf{x}\Big] &\equiv \mathsf{MI}(\mathbf{y},\mathbf{x}^{\star}) \quad \text{(Parallel ES)} \\ \mathsf{H}\big[\mathbf{y}\big|\mathcal{D}_{t},\mathbf{x}\big] - \mathbb{E}_{\mathbf{x}^{\star}}^{\star}\Big[\mathsf{H}\big[\mathbf{y}\big|\mathcal{D}_{t},\mathbf{x},\mathbf{x}^{\star}\big]\Big|\mathcal{D}_{t},\mathbf{x}\Big] &\equiv \mathsf{MI}(\mathbf{x}^{\star},\mathbf{y}) \quad \text{(Parallel PES)} \\ \\ &\frac{\mathsf{Multi-variate}}{\mathsf{Gaussian}} & \mathsf{Gaussian} &$$

Choose a set Q points $S_t = \{x_q\}_{q=1}^Q$ to minimize the entropy of x^* .

$$\begin{split} \mathsf{H}\big[\mathbf{x}^{\star}\big|\mathcal{D}_{t}\big] - \mathbb{E}_{\mathbf{y}}\Big[\mathsf{H}\big[\mathbf{x}^{\star}\big|\mathcal{D}_{t} \cup \{\mathbf{x}_{q},y_{q}\}_{q=1}^{Q}\big]\Big|\mathcal{D}_{t},\mathbf{x}\Big] &\equiv \mathsf{MI}(\mathbf{y},\mathbf{x}^{\star}) \quad \text{(Parallel ES)} \\ \mathsf{H}\big[\mathbf{y}\big|\mathcal{D}_{t},\mathbf{x}\big] - \mathbb{E}_{\mathbf{x}^{\star}}^{\star}\Big[\mathsf{H}\big[\mathbf{y}\big|\mathcal{D}_{t},\mathbf{x},\mathbf{x}^{\star}\big]\Big|\mathcal{D}_{t},\mathbf{x}\Big] &\equiv \mathsf{MI}(\mathbf{x}^{\star},\mathbf{y}) \quad \text{(Parallel PES)} \\ \\ \frac{\mathsf{Multi-variate}}{\mathsf{Gaussian}} & \mathsf{Gaussian} \\ \mathsf{distribution} \end{split}$$

Choose a set Q points $S_t = \{x_q\}_{q=1}^Q$ to minimize the entropy of x^* .

$$\begin{split} \mathsf{H}\big[\mathbf{x}^{\star}\big|\mathcal{D}_{t}\big] - \mathbb{E}_{\mathbf{y}}\Big[\mathsf{H}\big[\mathbf{x}^{\star}\big|\mathcal{D}_{t} \cup \{\mathbf{x}_{q},y_{q}\}_{q=1}^{Q}\big]\Big|\mathcal{D}_{t},\mathbf{x}\Big] &\equiv \mathsf{MI}(\mathbf{y},\mathbf{x}^{\star}) \quad \text{(Parallel ES)} \\ \mathsf{H}\big[\mathbf{y}\big|\mathcal{D}_{t},\mathbf{x}\big] - \mathbb{E}_{\mathbf{x}^{\star}}^{\star}\Big[\mathsf{H}\big[\mathbf{y}\big|\mathcal{D}_{t},\mathbf{x},\mathbf{x}^{\star}\big]\Big|\mathcal{D}_{t},\mathbf{x}\Big] &\equiv \mathsf{MI}(\mathbf{x}^{\star},\mathbf{y}) \quad \text{(Parallel PES)} \\ \\ &\underbrace{\mathsf{Multi-variate}_{\mathsf{Gaussian}}}_{\mathsf{distribution}} &\underbrace{\mathsf{Approximated by}_{\mathsf{sampling from }p(\mathbf{x}^{\star}|\mathcal{D}_{t})} \end{split}$$

Choose a set Q points $S_t = \{x_q\}_{q=1}^Q$ to minimize the entropy of x^* .

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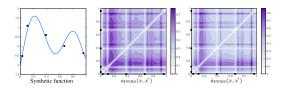
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$$\alpha(\mathbf{X}) = \log |\mathbf{V}^{\mathrm{PD}}(\mathbf{X})| - \frac{1}{M} \sum_{m=1}^{M} \log |\mathbf{V}^{\mathrm{CPD}}(\mathbf{X}|\mathbf{x}^{\star}_{(m)})|$$

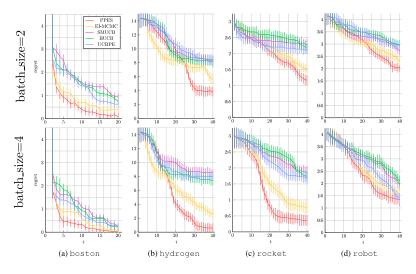
Choose a set Q points $\mathcal{S}_t = \{\mathsf{x}_q\}_{q=1}^Q$ to minimize the entropy of x^\star .

It is possible to compute the gradient of $\alpha(\cdot)$ w.r.t. each $x_a \in \mathcal{S}_t!$

Parallel Predictive Entropy Search: Level Curves



Parallel Predictive Entropy Search: Results



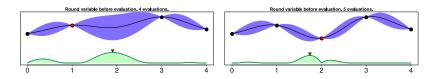
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A naive approach is to round the suggested value to the closest integer or to the closest one-hot encoding.

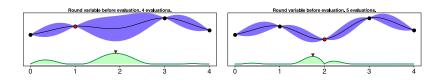
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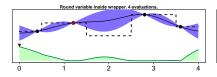
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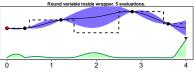
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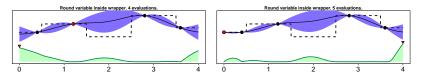
The BO algorithm may get stuck and may always perform the next evaluation at the same input location!

Rounding inside of the wrapper works but makes the objective flat!





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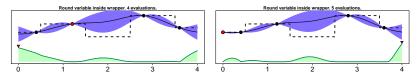


A modified GP covariance function accounts for this:

$$C_{\text{new}}(x_n, x_{n'}) = C(T(x_n), T(x_{n'}); \theta)$$

where $T(\cdot)$ does the rounding to the closest integer or one-hot encoding.

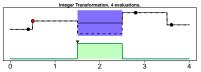
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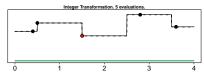


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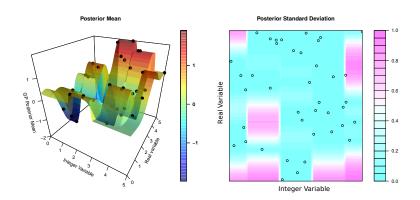
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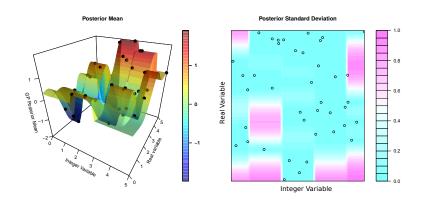


The GP predictive distribution is constant across all variables that lead to the same integer or one-hot-encoding.

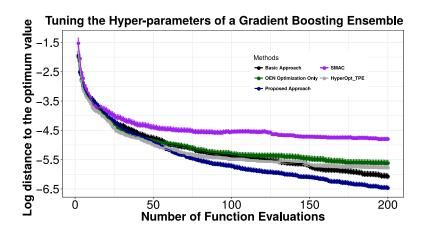
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Similar results for categorical variables!



One continuous variable and two integer-valued variables.

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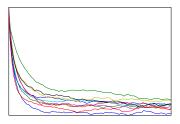
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Common aspects of many machine learning algorithms:

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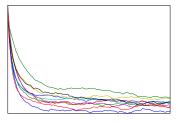
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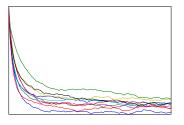
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Can we use partial training information and a model to determine which hyper-parameter configuration is going to be optimal?

Yes, that is precisely what Freeze-Thaw BO does!

(Swersky et al., 2014)



A GP Kernel for Training Curves

We want to specify a kernel that supports exponentially decaying functions of the form $\exp\{-\lambda t\}$ for $t, \lambda \geq 0$.

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The covariance between inputs t and t' is:

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where $\psi(\lambda; \alpha, \beta)$ is a gamma distribution with parameters α and β .

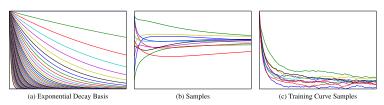
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$$p(\{y_n\}_{n=1}^N | \{x_n\}_{n=1}^N) = \int \left[\prod_{n=1}^N \mathcal{N}(y_n | f_n 1, K_{t_n}) \right] \mathcal{N}(f | m, K_x) df$$

where

$$x_n \equiv n$$
 configuration, $y_n \equiv n$ observed curve, $f_n \equiv n$ asymptotic value, $m \equiv prior$ asymptotic mean values, $K_{t_n} \equiv covariances$ for curve values, $K_x \equiv cov$. for asymptotic values

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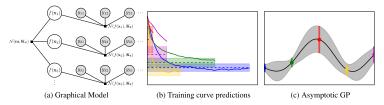
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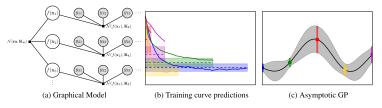
$$p(\{y_n\}_{n=1}^N | \{x_n\}_{n=1}^N) = \int \left[\prod_{n=1}^N \mathcal{N}(y_n | f_n 1, K_{t_n}) \right] \mathcal{N}(f|m, K_x) df$$

where

 $x_n \equiv n \text{ configuration}$, $y_n \equiv n \text{ observed curve}$, $f_n \equiv n \text{ asymptotic value}$, $m \equiv \text{prior asymptotic mean values}$, $K_{x_n} \equiv \text{covariances for curve values}$, $K_x \equiv \text{cov. for asymptotic values}$

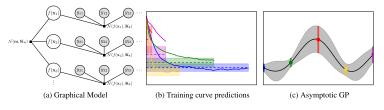
The joint distribution of $\{y\}_{n=1}^{N}$ and f is Gaussian and hence so it is the predictive distribution $p(f|\{y\}_{n=1}^{N})!$





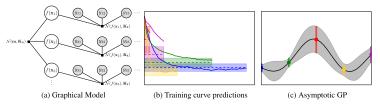
Bayesian Optimization:

▶ $p(f|\{y_n\}_{n=1}^N, \{x_n\}_{n=1}^N)$ determines asymptotic values.



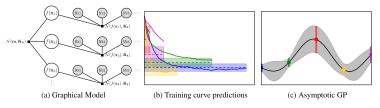
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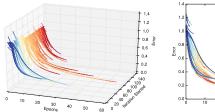
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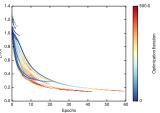
- ▶ $p(f|\{y_n\}_{n=1}^N, \{x_n\}_{n=1}^N)$ determines asymptotic values.
- This distribution can be used to make intelligent decisions!
- ► Shall we train more one configuration or shall we start a new one?
- ► A combination of EI and ES is used as the acquisition function.

(Swersky et al., 2014)

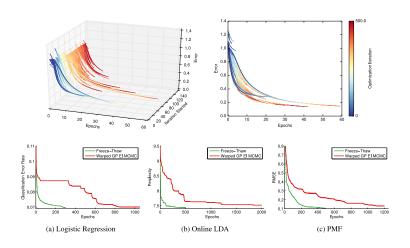


Freeze-Thaw BO in practice



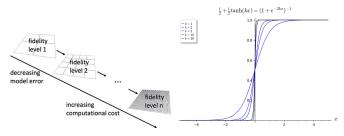


Freeze-Thaw BO in practice



(Swersky et al., 2014)

Multi-fidelity Bayesian optimization



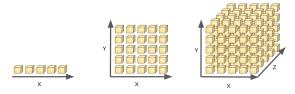
- Concept of Fidelity: Fidelity refers to the accuracy or reliability of the information, we use different levels of accuracy.
- **Example:** # layers in NNs, # of timesteps for DRL.
- We assume that lower fidelities are correlated with higher.
- ► **Cost-Efficiency:** Leveraging computationally cheaper versions of the functions to guide the search process.
- ➤ The trick: The acquisition function should balance exploration at cheaper fidelities with exploitation at the highest fidelity level.

Multi-fidelity Bayesian optimization example

- Trace-aware knowledge-gradient acquisition function.
- It values observations of a point (x) and a set of fidelities (S) according to the ratio of the reduction in expected loss that it induces, to its computational cost.
- It measures the value of information per unit cost of sampling.
- It uses a function L() to measure the extent to which observing trace information improves the quality of the solution. L(0) will be the minimum.
- Its analytical expression basically penalizes the cost wrt the information obtained:

$$takg(x,S) = \frac{L(0) - L(x,S)}{cost(x, max(S))}$$

High-dimensional Bayesian optimization

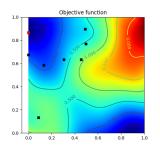


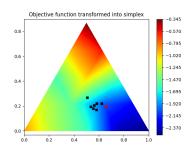
- ▶ GPs empirical performance tends to be lower if d > 7.
- ► The problem: The search space grows exponentially with the number of dimensions.
- ➤ The trick: We can project the high-dimensional problem into a lower-dimensional subspace that explains it well using embeddings.
- ► Find the hidden most explicative manifold for the data, then optimize there!
- Approaches differ in the type of embeddings (e.g. random), assumptions about the function (e.g. being a sum of functions), or use of models (Deep GP, GP-LVM.)

High-dimensional Bayesian optimization example

- Sparse Axis-Aligned Subspace Bayesian Optimization (SAASBO)
- Goal: Identify sparse subspaces relevant to modeling the unknown objective function.
- Assumption: High function variability being captured by axis-aligned blocks of input features.
- ► **Method:** Use complex GP prior to consider a smaller class of functions.
- Effect: Turn most non-explicative dims off.
- Integration: Perform hyper-parameter sampling with NUTS and EI.

Bayesian optimization in a simplex (Portfolio optimization)





- Common financial metrics as Sharpe or Sortino ratio can be configured for a specific portfolio.
- For example using real-time ESG values of the assets.
- Garrido-Merchán, E. C., Piris, G. G., & Vaca, M. C. (2023). Bayesian optimization of ESG (Environmental Social Governance) financial investments. Environmental Research Communications, 5(5), 055003.

Conclusions and Further Work

- ▶ BO is a state-of-the-art class of methods used to optimize expensive and noisy black-box functions.
- We can generalize BO to tackle advanced scenarios: parallel constrained multi-obj, high-dim, multi-fidelity...
- ▶ BO can be applied in a wide array of applications: ML, DRL, finance, robotics, materials, business operations...
- Further work topics: causality, meta-BO, transfer learning, adaptation to specific domains.



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Thank you for your attention.